

## CH. 19 ENERGY + MOMENTUM IN RIGID BODY DYNAMICS

### SECTION 19-1 WORK + ENERGY

WORK = TRANSLATION:

$$U_{12} = W = F_{\parallel} d = \cancel{F \cdot r}^{\text{dot product}} = |F|/r \cos(\theta) \quad \left\{ \text{ASSUMPTION } \theta = \text{constant} \right\}$$

$\curvearrowleft$  JOULE

$$U_{12} = W = \int F \cdot dr$$

$$\text{ROTATION: } U_{12} = W_p = M\theta = M\Delta\theta_{12} = \int M d\theta$$

$\curvearrowleft$  JOULES, FT-LBS

POWER = TRANSLATION:

$$P = \frac{\Delta W}{T} = \frac{\Delta U_{12}}{T} = \frac{F \cdot r}{T} = F \cdot V = |F|/V \cos \theta \quad \left\{ \theta = \text{constant} \right\}$$

$\curvearrowleft$  WATTS

ROTATION:

$$P = M \overset{\text{MOMENT APPLIED}}{\overset{\curvearrowleft}{\omega}} \overset{\text{ANGULAR VELOCITY}}{\underset{\curvearrowleft}{\omega}} = \int M d\omega \quad \left\{ 2D \text{ CASE} \right\}$$

AVERAGE POWER

$$P_{\text{avg}} = \frac{T_2 - T_1}{\Delta t} = \frac{TE_1 - TE_2}{\Delta t} \quad \text{KENETIC ENERG OF A SYSTEM (NOT CONSIDERING CONSERVATIVE FORCES)}$$

CONSERVATION OF ENERGY  $\left\{ \text{INCLUDES - PRINCIPLE OF WORK + ENERGY} \right\}$

$$TE_1 + W = TE_2$$

$$KE_1 + RE_1 + PE_1 + W = KE_2 + RE_2 + PE_2$$

$$KE = \frac{1}{2} m v^2 \quad RE = \frac{1}{2} I \omega^2 \quad PE = mgh = \frac{1}{2} kx^2$$

KINEMATIC RELATIONSHIPS - DEFINITIONS

$a^2 + b^2 = c^2$  (RIGHT TRIANGLE), LAW OF SINES,

$$v_s^2 = v_i^2 + 2as$$

$$s = r\theta$$

ROLLING   $v = rw$   
 $a_t = rd$

SECTION 19-1 NOTES (CONT.)

• NOTE EXAMPLE 19.2 - WORKED OUT Pg. 425.

Critical thinking note.

$$TE_1 + W = TE_2$$

$$PE_1 + O_i + M\theta = KE_{CM} + RE_{FW} + RE_{RW} + PE_2$$

$$M\theta = 2 \left( \frac{1}{2} I_{CM} w^2 \right) + \frac{1}{2} m V_{cm}^2$$

$$V = rw$$

$$S = r\theta$$

19-6 HOMEWORK EXAMPLE:  $I = 540 \text{ kg}\cdot\text{m}^2$ ,  $M = 6500 - 20\theta$  ( $n, b$ )  
 $\theta = 10 \text{ rev} \left( \frac{2\pi \text{ rad}}{1 \text{ rev}} \right) = 62.8 \text{ rad}$

FIND:  $w = ? \text{ RPM} @ \theta = 62.8 \text{ rad}$

SOLUTION! CONSERVATION OF ENERGY EQUATION

$$TE_1 + W = TE_2$$

$$PE_1 + O + W_p = PE_2 + KE + RE_2 \Rightarrow W_p = \frac{1}{2} I w^2$$

$$W_p = M\theta = \int_M d\theta = \int_0^\theta (6500 - 20\theta) d\theta = 6500\theta - 10\theta^2$$

$$W_p = 3.69 \cdot 10^5 \text{ D.J. (J)}$$

NOW USING EQUATION #1

$$W_p = \frac{1}{2} I w^2$$

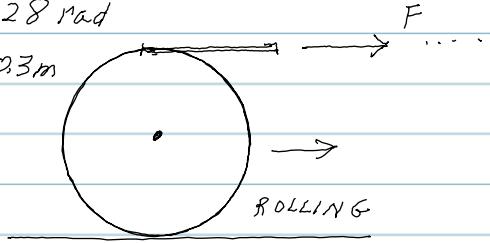
$$w = \sqrt{\frac{2W_p}{I}} = \sqrt{\frac{2(3.69 \cdot 10^5 \text{ J})}{540 \text{ kg}\cdot\text{m}^2}} = 37 \frac{\text{rad}}{\text{sec}} \left( \frac{10 \text{ RPM}}{1.047 \frac{\text{rad}}{\text{s}}} \right) = \underline{\underline{353 \text{ RPM}}}$$

SECTION 19-1 HOMEWORK EXAMPLES (CONT.)

19-22 GIVEN: SOLID DISK,  $F = 500\text{N}$ ,  $\theta = 1 \text{ rev} = 6.28 \text{ rad}$

$$I_{cm} = \frac{1}{2} mr^2, m = 100\text{kg}, r = 300\text{mm} = 0.3\text{m}$$

FIND:  $w = ? @ \theta = 1 \text{ rev.}$



SOLUTION: CONSERVATION OF ENERGY

$$\circ + W = TE_F = KE_{T2} + RE_z$$

$$\textcircled{1} \quad W = \frac{1}{2} mv^2 + \frac{1}{2} I w^2$$

$$W = F \cdot d = F (2 \cdot \text{CIR}M) = F \cdot 2 \cdot 2\pi r = (4\pi Fr) = 4\pi \cdot 500\text{N} \cdot 0.3\text{m}$$

$$W = 1885 \text{ J}$$

$$\textcircled{1} \quad 1885 \text{ J} = \frac{1}{2} mv^2 + \frac{1}{2} I w^2 \quad \text{KINETIC EQ.: } V = rw$$

$$1885 \text{ J} = \frac{1}{2} m(rw)^2 + \frac{1}{2} \left[ \frac{1}{2} mr^2 \right] w^2 = \frac{1}{2} mr^2 w^2 + \frac{1}{4} mr^2 w^2 = \frac{3}{4} mr^2 w^2$$

$$w^2 = \frac{1885 \text{ J}}{\frac{3}{4} mr^2} = \frac{1885 \text{ J}}{.75(100\text{kg})(0.3\text{m})^2} = 279.3 \frac{\text{rad}^2}{\text{s}^2}$$

$$w = 16.7 \frac{\text{rad}}{\text{s}} \text{ CW}$$

SECTION 19-2 IMPULSE + MOMENTUM NOTES

LINEAR IMPULSE &  
MOMENTUM

$$F\Delta t = m\Delta v = \Delta mv$$

$$P = mv$$

$$\int F dt = mav$$

ANGULAR IMPULSE &  
MOMENTUM

$$m\Delta t = I_{cm} \Delta w = \Delta I_{cm} w$$

$$H_{cm} = I_{cm} w$$

$$\int m dt = \Delta I_{cm} w$$

ISOLATED SYSTEM

MOMENTUM IS CONSERVED

$$\sum m v_i = \sum m v_f$$

ANGULAR IS CONSERVED ABOUT ANY  
FIXED POINT -  $H_0 \Rightarrow \sum I_{0i} w_i = \sum I_{0f} w_f$

IF COMMON CM (CENTER OF MASS)

$$H_0 = I_{cm} w \Rightarrow I_1 w_1 = I_2 w_2$$

SECTION 19-2 HOMEWORK EXAMPLES

19-51 GIVEN:  $m = 122 \text{ kg}$ ,  $I_{cm} = 45 \text{ kg}\cdot\text{m}^2$ ,  $\Delta T = 0.25$ ,  $r = 300 \text{ mm} = 0.3 \text{ m}$   
 $w = 1 \text{ RPM} \left( \frac{1.047 \frac{\text{rad}}{\text{s}}}{10 \text{ RPM}} \right) = 0.1047 \frac{\text{rad}}{\text{s}}$

FIND:  $F_{Av} = ?$   $V_{cm2} = ?$

SOLUTION:  $\sum M_{cm} \Delta T = \Delta I_{cm} w = I_{cm} w_2 - I_{cm} w_1$

$$+ (F)(3m) \Delta T = I_{cm} w_2$$

$$F = \frac{I_{cm} w_2}{3 \Delta T} = \frac{(45 \text{ kg}\cdot\text{m}^2)(0.1047 \frac{\text{rad}}{\text{s}})}{(0.3 \text{ m})(0.25)} = 78.5 \text{ N}$$



b) FIND:  $V_{cm} = ?$

SOLUTION: LINEAR IMPULSE  $F \Delta T = m \Delta V = m V_2 - m V_1$

$$V_2 = \frac{F \Delta T}{m} = \frac{(78.5 \text{ N})(0.25)}{122 \text{ kg}} = 0.13 \frac{\text{m}}{\text{s}}$$

19-57 GIVEN:  $F_F = 0$  (NO SLIPPING)

FIND:  $h = ?$  IN TERMS OF "r"

SOLUTION: THINGS THAT ARE TRUE

$$\text{LINEAR: } F \Delta T = m \Delta V = m V_2 - m V_1 = m V_2$$

$$\textcircled{1} \quad F \Delta T = m V_2$$

$$\text{ANGULAR: } m \Delta T = I \Delta \omega = I_{cm} w_2 - I_{cm} w_1 = I_{cm} w_2$$

$$(F)(h-r) \Delta T = I_{cm} w_2 \quad (\text{NOTE: } I_{cm} = \frac{2}{5} m r^2)$$

$$\textcircled{2} \quad (F)(h-r) \Delta T = \frac{2}{5} m r^2 w_2 \Rightarrow F \Delta T = \frac{\frac{2}{5} m r^2 w_2}{(h-r)}$$

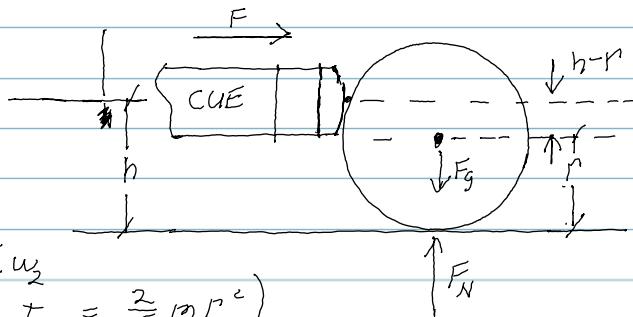
COMBINE  $\textcircled{1} + \textcircled{2}$  USE PDT

$$\cancel{m V_2} = \frac{\frac{2}{5} m r^2 w_2}{(h-r)}$$

$$\underline{(\text{KINEMATIC EQUATION } V = r \omega)}$$

$$\cancel{m \omega_2} = \frac{\frac{2}{5} m r^2 \omega_2}{h-r} \Rightarrow 1 = \frac{\frac{2}{5} r}{(h-r)} \Rightarrow (h-r) = \frac{2}{5} r$$

$$h = r + \frac{2}{5} r = \frac{7}{5} r = 1.4 r : 40\% \text{ ABOVE } "r"$$



SECTION 19-3 IMPACTS

COEFFICIENT OF RESTITUTION

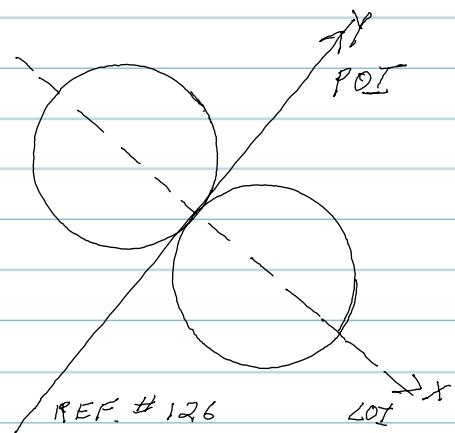
$$e = \frac{\text{SEPARATION VELOCITY}}{\text{APPROACH VELOCITY}} = \frac{V'_{BP} - V'_{AP}}{V_{AP} - V_{BP}}$$

↑ ALONG LOI

ELASTIC PROCESS

$$e=1 \quad \text{FULLY ELASTIC} \rightarrow KE_b = KE_a$$

$$e=0 \quad \text{FULLY PLASTIC} \rightarrow \text{OBJECT STICK TOGETHER}$$



REF. # 126

RESTRICT OUR DISCUSSION TO IMPACTS W/ A FIXED POINT.

SPECIAL CASES

1 - ISOLATED SYSTEM  $\sum H_{oB} = \sum H_{oA}$

2 - FIXED POINT ON ONE OBJECT -  $\sum H_{oB} = \sum H_{oA}$

